

## Embodiment and Language Acquisition in Humanoid Robots

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COGNITIVE  
 ROBOTICS  
 WITH  
 PLYMOUTH  
 UNIVERSITY



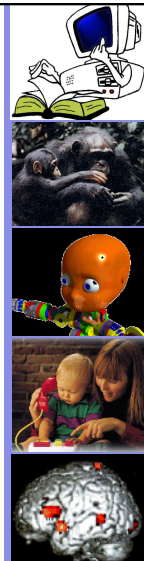
## Overview

1. Embodied developmental learning
  - Embodiment and language
  - The Chinese Room Experiment
  - Developmental robotics and the iCub
2. Experiments with the iCub
  - Language and category learning
  - Action and syntax learning
  - Space and numbers
3. Conclusions

## Language and Cognition

There are two opposing theoretical approaches to the study of language and cognition (in humans and robots)

1. **SYMBOLIC**: Cognition is autonomous and **amodal** (e.g. Fodor, Chomsky, Landauer & Dumais)
2. **GROUNDING**: Language and cognition is **grounded** in the world/body (eg. Cangelosi & Harnad, Gallese & Lakoff, Pulvermuller, Glenberg, Roy, Rohlfing et al.)



## Language and Machines

- Robots can be easily **pre-programmed** to memorise a dictionary, but cannot fully understand the language they use



Siri. Apple  
 Your wish is its command.





### Chinese Room Experiment in Palma

**Question:** *quanti anni havi la X ?*

#### Dictionary

- *picciotta*: setti anni, picca pitittu, maciari hovu
- *za'nzina*: settanta anni, assai pitittu, maciari haddina
- *haddina*: dui anni, assai pitittu, maciari simenza
- *anni*: dui, setti, settanta
- *pitittu*: assai, picca
- *maciari*: hovu, haddina, simenza

#### Reply Rule Book

- *quanti anni havi la X ?* → la X havi A anni
- *quantu pitittu havi la X ?* → la X havi B pitittu
- *soccu voli maciari la X ?* → la X voli maciari C

### Chinese Room Experiment

#### Questions

- *quanti anni havi la picciotta ?*
- *quanti anni havi la za'nzina ?*
- *quanti anni havi la haddina ?*
- *quantu pitittu havi la picciotta ?*
- *quantu pitittu havi la za'nzina ?*
- *quantu pitittu havi la haddina ?*
- *soccu voli maciari la picciotta ?*
- *soccu voli maciari la za'nzina ?*
- *soccu voli maciari la haddina ?*

#### Answers

- la picciotta havi setti anni
- la za'nzina havi settanta anni
- la haddina havi dui anni
- la picciotta havi picca pituittu
- la za'nzina havi assai pitittu
- la haddina havi assai pitittu
- la picciotta voli maciari hovu
- la za'nzina voli maciari haddina
- la haddina voli maciari simenza

### Sicilian Room Experiment

#### Dictionary

- *picciotta*: setti anni, picca pitittu, maciari hovu
- *za'nzina*: settanta anni, assai pitittu, maciari haddina
- *haddina*: dui anni, assai pitittu, maciari simenza
- *anni*: dui, setti, settanta
- *pitittu*: assai, picca
- *maciari*: hovu, haddina, simenza



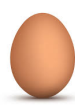
**picciotta**  
girl



**za'nzina**  
aunt



**haddina**  
chicken



**hovu**  
egg



**simenza**  
seeds



**assai**  
much



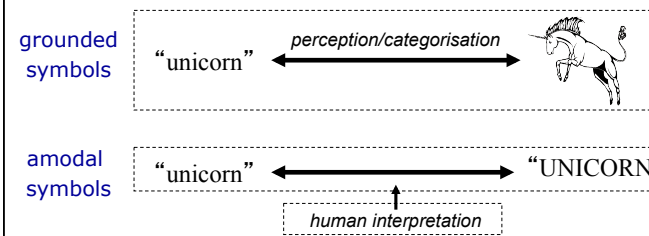
**picca**  
little

### The Symbol Grounding Problem

(Harnad 1990)

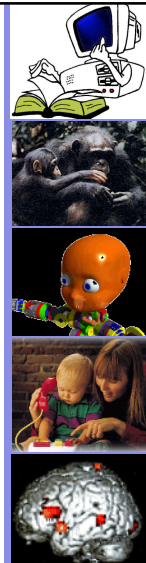
How can the meanings of the symbols (words) in a cognitive symbol system be *grounded* in something other than just further ungrounded symbols?

*To embody thought, a cognitive system must be autonomous, i.e. have direct and intrinsic symbol-meaning links*



## Learning & Development

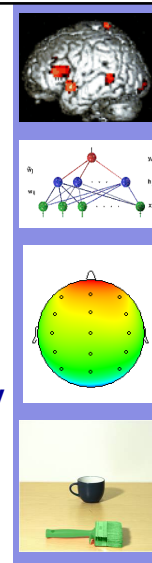
- Robots can be easily **pre-programmed** to memorise a dictionary, but cannot fully understand the language they use
- Children are **not** born with the knowledge of a language (Tomasello 2003)
- Children are **slow**, but efficient at learning a language



## Action and Language

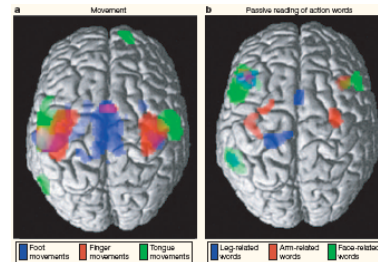
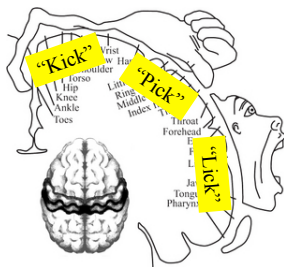
Robots are **separately** trained to handle linguistic and motor capabilities, but...

- The **brain integrates** language and sensorimotor knowledge (Pulvermuller 2003)
- Action and perception are **intrinsically linked** – microaffordances (Ellis et al. 2004)

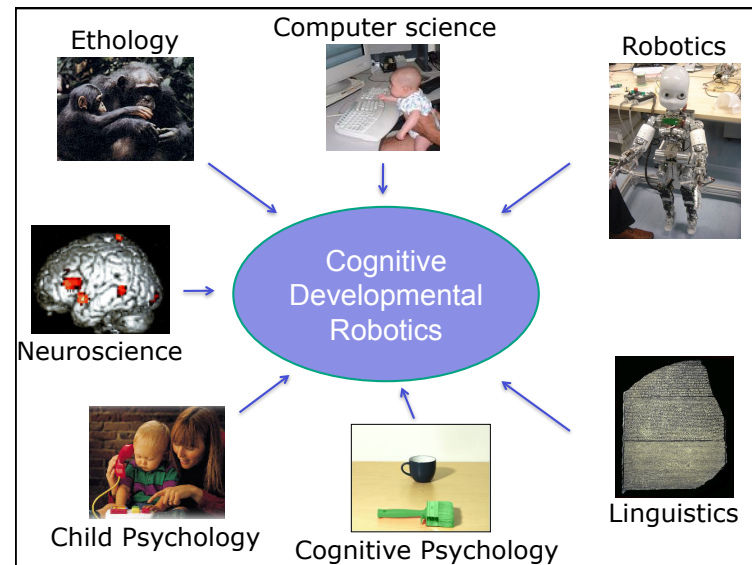


## Words and Actions in the Brain

Verbs/Nouns and Abstract/Concrete words (Cappa & Perani 2003)  
 Semantic Somatotopy of action words (Pulvermuller 2003)

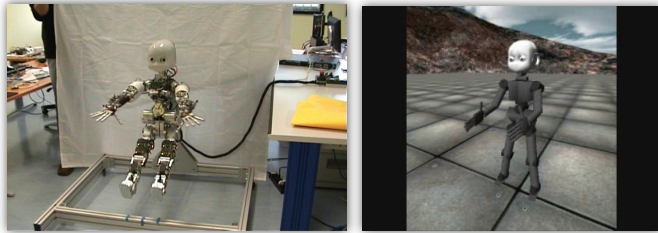


“Kick”, “Pick”, “Lick”



## ***Simulated and Physical iCub***

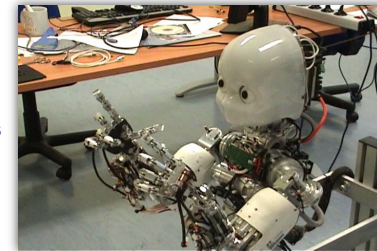
- Toddler robot (Metta et al. 2004)
- Physical and simulated iCub (Tikhanoﬀ et al. 2004)
- Action/Language studies in ITALK project



www.robotcub.org

## ***iCub: Degrees of freedom***

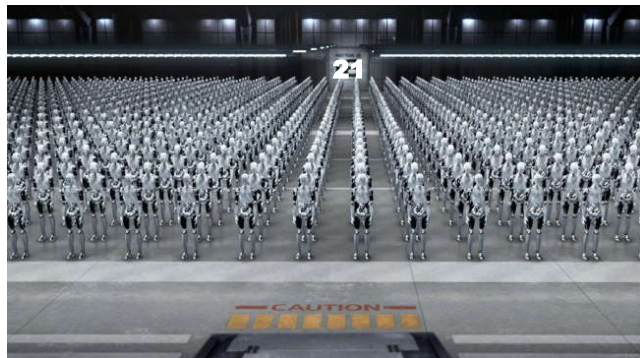
- Head: vergence, common tilt + 3 dof neck
- Arms: 7 dof each
  - Shoulder (3), elbow (1), wrist (3)
- Hands: 9 dof each ► 19 joints
  - 5 fingers ► underactuated
- Legs: 6 dof each
  - Hip (3), knee (1), ankle (2)
- Waist: 3 dof



$\Sigma = 53 \text{ dof}$  (not counting the facial expressions)



## ***Benchmark Robotics Platform (21+ iCubs in 2012)***



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## Body Posture and Cognition



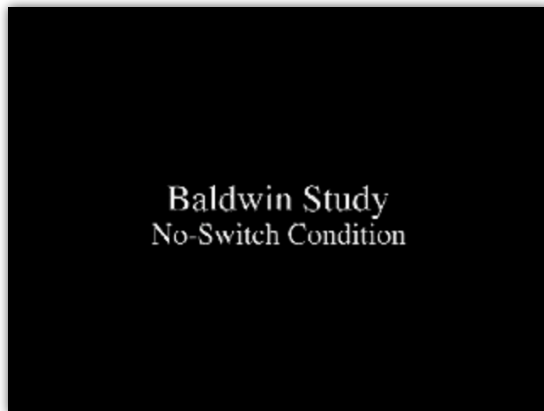
- Challenges to the idea that names are only associated to the object being attended to when the name is heard (Smith & Samuelson 2010)
- The cognitive system uses the body's orientation in space to select remembered objects

### “Body as cognitive hub” Hypothesis

(Smith 2005; Morse et al. 2010)

*Embodied representations (body map)  
cross-link various modalities  
(e.g. visual, tactile, sound maps)*

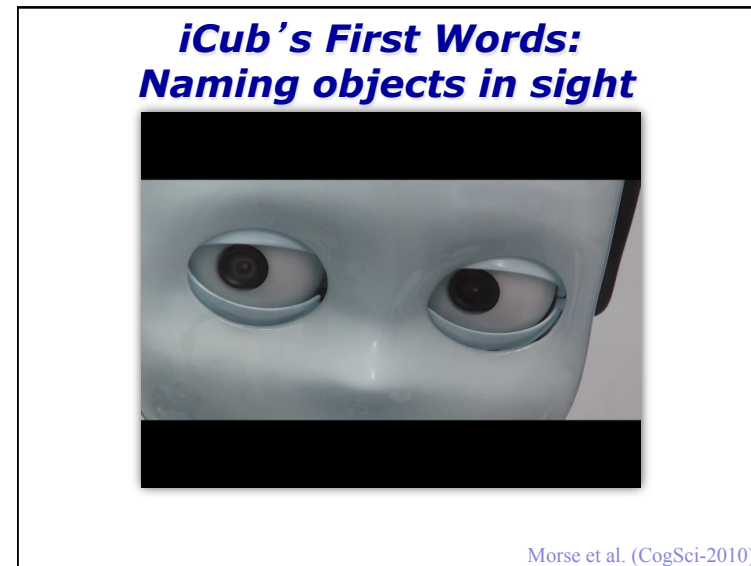
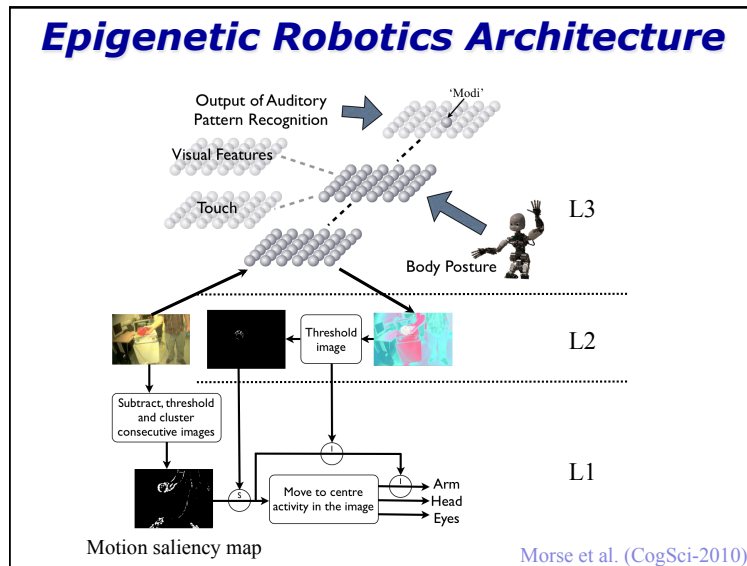
## Baldwin ‘Modi’ Experiment



D. Baldwin (1993); Smith & Samuelson (2010)

		Switch			
		Left	Right	Left	Right
Step 1					
Step 2					
Step 3					
Step 4					
Step 5	look at the MODI			look at the MODI	
Step 6					
Step 7					
Test		Where's the MODI?		Where's the MODI?	

Consistent spatial cue **73%**      No consistency **46%**



### iCub 'Modi' : Predictions

- 4 Experiments
  - S&S Exp1: No switch
  - S&S Exp1: Switch
  - S&S Exp2: Control
  - S&S Exp2: Switch
- Model prediction
  - Changes in body posture are predictors of sensory change
  - Changing position from sitting to standing should remove the effect, and sitting again should reinstate it

Experiment	Robot data	Human Data
Exp1 No Switch	~80	~70
Exp1 Switch	~55	~45
Exp2 Control	~95	~80
Exp2 Switch	~45	~40

### Psychological modelling & Developmental learning for action-language integration and generalization

Epigenetic Robotics Architecture (ERA)

- Posture/Space biases
- Mutual exclusivity
- Fast-Mapping
- Language and variability effects
- Proto-Compositionality and generalization

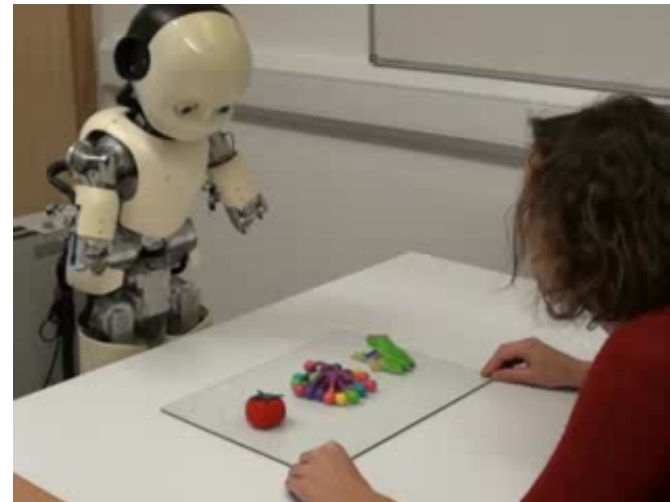
## Embodied Category Learning



## Mutual Exclusivity And Category Variability

Single	<i>hux</i>		Single	<i>doff</i>		Single	<i>cheem</i>	
	Narrow	Variable		Narrow	Variable		Narrow	Variable
			Extension objects					
	<i>hux</i>		<i>doff</i>		<i>cheem</i>			

With K. Twomey (Sussex Babylab)





## Overview

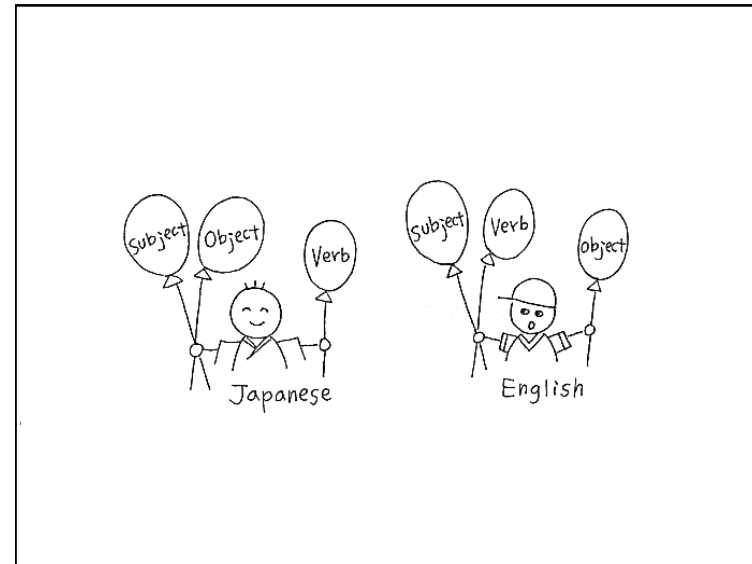
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- **Action and syntax learning**
- Space and numbers

### 3. Conclusions



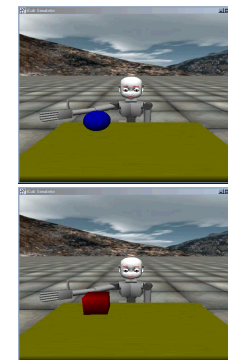
## Learning from Word Order

- Language development: Meaning from a **structural cue** like word order:
  - category information, e.g. *the N*, *look at the N*
  - semantic roles, e.g. *John kisses Mary*
  - children use such cues (Gomez 2007; StClair et al. 2010)
- iCub modelling of word order for information on
  - grammatical category (adjective - noun)
  - semantic category (colour - shape)

## Learning from Word Order Cues:

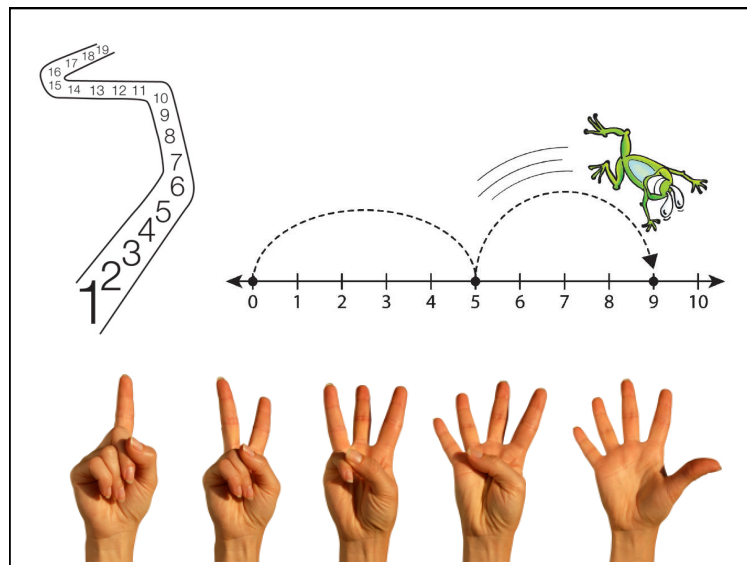
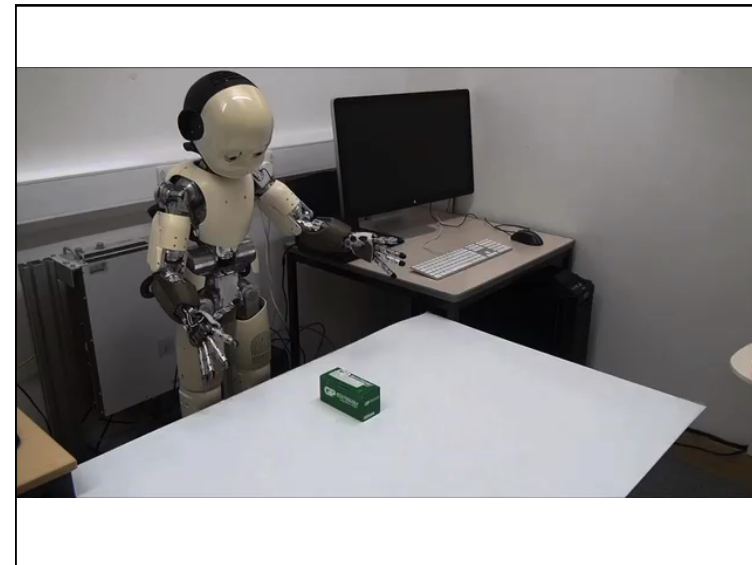
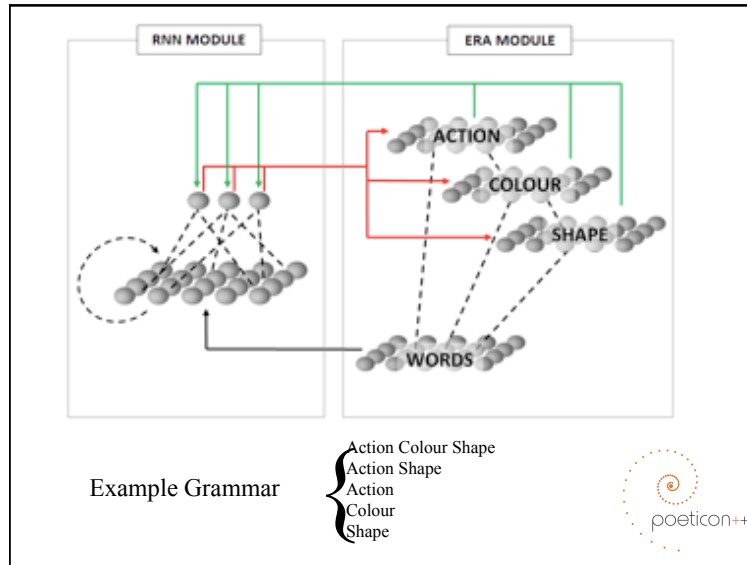
### Language training:

- *touch ball* [V-N]
- *touch cube* [V-N]
- *touch red* [V-A]
- *touch green* [V-A]
- *touch green ball* [V-A-N]
- *touch green cube* [V-A-N]
- *touch red ball* [V-A-N]
- *touch red cube* [V-A-N]



### Positive + negative sentences

Environment	Language input	Action
RED CUBE	"touch red cube"	Touch the box
GREEN CUBE	"touch green ball"	Do not touch



### Space and Gestures

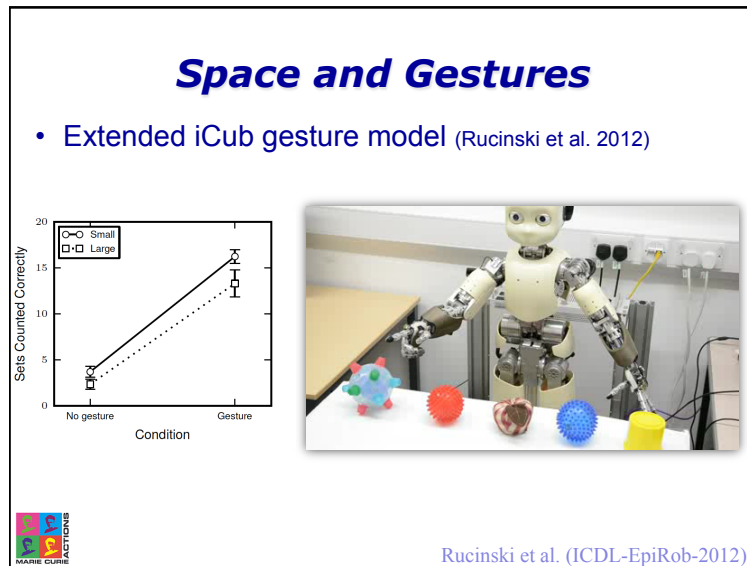
- Gestures in counting: Pointing, touching, moving:
  - integral part of the development of number knowledge
  - spontaneous and omnipresent
  - prevention disrupts counting procedure
  - physical contact matters
  - development: 2-4-6 year-olds
  - active vs passive gesture

Condition	Sets Counted Correctly
No Gesture	~2.0
Puppet Point	~3.0
Child Point	~3.2
Puppet Touch	~3.8
Child Touch	~4.0

A photograph of a young child pointing at a calendar on a wall. The calendar shows numbers from 1 to 30, with the child's hand pointing to the number 10. The calendar is titled 'NUMBER' and 'NUMBER'.

Alibali & DiRusso (1999)

Photo: JewelAmclaudius, youtube.com



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## Take Home Message

- Embodied Language Learning
  - Embodiment cues in development
  - “Body as Cognitive Hub” hypothesis
  - Embodied Words and Numbers
  - Close match with empirical data
- Open challenges
  - Open-ended, cumulative learning, larger lexicons and cognitive repertoires
  - Brain and language
  - Generalisation and creativity
  - Robot companion applications



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